



TITLE:

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# Eigenvalue Problem related to Euler-Bernoulli Equation with Joint Boundary Condition

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## Abstract

We consider the control system of two vibrating beams which are coupled at a joint. The displacement of the beam is described by an Euler-Bernoulli equation with control applied at a coupled point. Our purpose is to argue the controllability of the system. To this purpose, we discuss the eigenvalue problem related to this system.

## 1 Introduction

Let us consider the controllability problem for a system coupled by Euler-Bernoulli beams. For  $m \in (0, 1)$ , we put  $x_0 = 0$ ,  $x_1 = m$  and  $x_2 = 1$ . The displacement of each beam at time  $t$  is described by  $y_i(x, t)$  on  $I_i = (x_{i-1}, x_i)$ ,  $i = 1, 2$ , and satisfies the Euler-Bernoulli equation:

$$\rho_i \ddot{y}_i + T_i y_i^{(4)} = 0 \quad \text{on } I_i \times (0, T) \quad (1)$$

where  $\dot{y}_i(x, t) = \partial y_i(x, t) / \partial t$ ,  $y_i^{(k)}(x, t) = \partial^k y_i(x, t) / \partial x^k$ .  $\rho_i$  is mass density and  $T_i$  is flexural rigidity respectively on  $I_i$ . Let both ends be clamped:

$$(B_0 y)(t) := (y_1(0, t), y_1^{(1)}(0, t), y_2(1, t), y_2^{(1)}(1, t)) = 0. \quad (2)$$

At the coupled point  $x = m$ , we apply control  $F = (f_1, f_2, f_3, f_4)$  as follows:

$$\left. \begin{aligned} (B_1 y)(t) &:= y_1(m, t) - y_2(m, t) = f_1(t), \\ (B_2 y)(t) &:= y_1^{(1)}(m, t) - y_2^{(1)}(m, t) = f_2(t), \\ (B_3 y)(t) &:= T_1 y_1^{(2)}(m, t) - T_2 y_2^{(2)}(m, t) = f_3(t), \\ (B_4 y)(t) &:= T_1 y_1^{(3)}(m, t) - T_2 y_2^{(3)}(m, t) = f_4(t). \end{aligned} \right\} \quad (3)$$

Initial condition is given as follows

$$y_i(x, 0) = y_i^0(x), \quad \dot{y}_i(x, 0) = y_i^1(x), \quad x \in I_i, \quad i = 1, 2. \quad (4)$$

We assume that controls  $f_i$  belong to  $L^2(0, T)$ ,  $i = 1, 2, 3, 4$ . In this paper, we treat controllability of the above system. Roughly speaking, the system (1)(2)(3)(4) is controllable if for any initial value  $(y_i^0, y_i^1)$  and final value  $(z_i^0, z_i^1)$ ,  $i = 1, 2$ , there exists a control  $F = (f_1, f_2, f_3, f_4)$  such that the corresponding solution of the system (1)(2)(3)(4) satisfies the final condition  $(y_i(x, T), \dot{y}_i(x, T)) = (z_i^0(x), z_i^1(x))$ ,  $i = 1, 2$ .

## 2 Eigenvalue Problem

Let us identify  $v \in L^2(I)$  with  $\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \in H = L^2(I) = L^2(I_1) \times L^2(I_2)$  where  $v_i = v|_{I_i}$ ,  $i = 1, 2$ ,  $I_1 = (0, m)$ ,  $I_2 = (m, 1)$ . Then  $H$  becomes a Hilbert space with inner product

$$(v, w) = \rho_1(v_1, w_1)_{L^2(I_1)} + \rho_2(v_2, w_2)_{L^2(I_2)} \quad \text{for } v = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}, w = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} \in H.$$

We define an operator  $A$  in  $H$  by

$$Av = \begin{pmatrix} (T_1/\rho_1)v_1^{(4)} \\ (T_2/\rho_2)v_2^{(4)} \end{pmatrix} \quad \text{for } v = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \in \mathcal{D}(A) := H^4(I_1) \times H^4(I_2)$$

and an operator  $\mathcal{A}$  by restricting  $A$  to

$$\mathcal{D}(\mathcal{A}) := \{v \in H^4(I_1) \times H^4(I_2); B_0v = 0, Bv := (B_1v, B_2v, B_3v, B_4v) = 0\}.$$

For this operator  $\mathcal{A}$ , we have

**Lemma 1** *The operator  $\mathcal{A}$  is a selfadjoint operator in  $H$  with compact resolvent.*

The proof of this lemma is easy to verify.

Let  $\lambda$  be an eigenvalue for  $\mathcal{A}$  with corresponding eigenfunction  $\phi$ . Then we have

$$\mathcal{A}\phi = \lambda\phi \tag{1}$$

with boundary conditions

$$B_0\phi = 0, \quad B\phi = 0. \tag{2}$$

We introduce functions  $C_{\pm}, S_{\pm}$  by

$$C_{\pm}(\theta) := \frac{\cosh \theta \pm \cos \theta}{2}, \quad S_{\pm}(\theta) := \frac{\sinh \theta \pm \sin \theta}{2} \quad \text{for } \theta \in \mathbb{R}.$$

Let  $\phi_i = \phi|_{I_i}$ ,  $\alpha_i = (\rho_i/T_i)^{\frac{1}{4}}$ ,  $i = 1, 2$ . A system of fundamental solutions to (1) in each  $I_i$  is given by  $\{C_{\pm}(\alpha_i\omega(x - x_{i-1})), S_{\pm}(\alpha_i\omega(x - x_{i-1}))\}$  and we have

$$\left. \begin{aligned} \phi_i(x) &= (p_1^i C_+ + p_2^i S_+ + p_3^i C_- + p_4^i S_-)(\alpha_i\omega(x - x_{i-1})), \\ (\phi_i)^{(1)}(x) &= \alpha_i\omega(p_1^i S_- + p_2^i C_+ + p_3^i S_+ + p_4^i C_-)(\alpha_i\omega(x - x_{i-1})), \\ (\phi_i)^{(2)}(x) &= \alpha_i^2\omega^2(p_1^i C_- + p_2^i S_- + p_3^i C_+ + p_4^i S_+)(\alpha_i\omega(x - x_{i-1})), \\ (\phi_i)^{(3)}(x) &= \alpha_i^3\omega^3(p_1^i S_+ + p_2^i C_- + p_3^i S_- + p_4^i C_+)(\alpha_i\omega(x - x_{i-1})) \end{aligned} \right\}$$

for  $x \in I_i$  where  $\omega = \lambda^{\frac{1}{4}}$ . By (2), we have  $p_1^1 = p_2^1 = 0$  and therefore

$$\left. \begin{aligned} \phi_1(x) &= (p_3^1 C_- + p_4^1 S_-)(\alpha_1\omega x), \\ (\phi_1)^{(1)}(x) &= \alpha_1\omega(p_3^1 S_+ + p_4^1 C_-)(\alpha_1\omega x), \\ (\phi_1)^{(2)}(x) &= \alpha_1^2\omega^2(p_3^1 C_+ + p_4^1 S_+)(\alpha_1\omega x), \\ (\phi_1)^{(3)}(x) &= \alpha_1^3\omega^3(p_3^1 S_- + p_4^1 C_+)(\alpha_1\omega x). \end{aligned} \right\} \tag{3}$$

By (2), we have

$$\gamma_2 \alpha_2 p^2 = \gamma_2 \alpha_2 \begin{pmatrix} p_1^2 \\ p_2^2 \\ p_3^2 \\ p_4^2 \end{pmatrix} = \begin{pmatrix} \gamma_2 \alpha_2 C_-^1(\omega) & \gamma_2 \alpha_2 S_-^1(\omega) \\ \gamma_2 \alpha_1 S_+^1(\omega) & \gamma_2 \alpha_1 C_-^1(\omega) \\ \gamma_1 \alpha_2 C_+^1(\omega) & \gamma_1 \alpha_2 S_+^1(\omega) \\ \gamma_1 \alpha_1 S_-^1(\omega) & \gamma_1 \alpha_1 C_+^1(\omega) \end{pmatrix} \begin{pmatrix} p_3^1 \\ p_4^1 \end{pmatrix} \quad (4)$$

where  $\gamma_i = T_i \alpha_i^2$ ,  $i = 1, 2$ ,  $\beta_1 = \alpha_1 m$ ,  $S_\pm^1(\omega) = S_\pm(\beta_1 \omega)$ ,  $C_\pm^1(\omega) = C_\pm(\beta_1 \omega)$ . By (2), we see

$$\begin{pmatrix} C_+^2(\omega) & S_+^2(\omega) & C_-^2(\omega) & S_-^2(\omega) \\ S_-^2(\omega) & C_+^2(\omega) & S_+^2(\omega) & C_-^2(\omega) \end{pmatrix} \begin{pmatrix} p_1^2 \\ p_2^2 \\ p_3^2 \\ p_4^2 \end{pmatrix} = 0, \quad (5)$$

where  $\beta_2 = \alpha_2(1 - m)$ ,  $S_\pm^2(\omega) = S_\pm(\beta_2 \omega)$ ,  $C_\pm^2(\omega) = C_\pm(\beta_2 \omega)$ . Let

$$\begin{aligned} D(\omega) &= \begin{pmatrix} D_{11}(\omega) & D_{12}(\omega) \\ D_{21}(\omega) & D_{22}(\omega) \end{pmatrix} \\ &:= \begin{pmatrix} C_+^2(\omega) & S_+^2(\omega) & C_-^2(\omega) & S_-^2(\omega) \\ S_-^2(\omega) & C_+^2(\omega) & S_+^2(\omega) & C_-^2(\omega) \end{pmatrix} \begin{pmatrix} \gamma_2 \alpha_2 C_-^1(\omega) & \gamma_2 \alpha_2 S_-^1(\omega) \\ \gamma_2 \alpha_1 S_+^1(\omega) & \gamma_2 \alpha_1 C_-^1(\omega) \\ \gamma_1 \alpha_2 C_+^1(\omega) & \gamma_1 \alpha_2 S_+^1(\omega) \\ \gamma_1 \alpha_1 S_-^1(\omega) & \gamma_1 \alpha_1 C_+^1(\omega) \end{pmatrix}. \end{aligned}$$

Then

$$\begin{aligned} D_{11}(\omega) &= (\gamma_2 \alpha_2 C_+^2 \cdot C_-^1 + \gamma_2 \alpha_1 S_+^2 \cdot S_-^1 + \gamma_1 \alpha_2 C_-^2 \cdot C_+^1 + \gamma_1 \alpha_1 S_-^2 \cdot S_+^1)(\omega), \\ D_{12}(\omega) &= (\gamma_2 \alpha_2 C_+^2 \cdot S_-^1 + \gamma_2 \alpha_1 S_+^2 \cdot C_-^1 + \gamma_1 \alpha_2 C_-^2 \cdot S_+^1 + \gamma_1 \alpha_1 S_-^2 \cdot C_+^1)(\omega), \\ D_{21}(\omega) &= (\gamma_2 \alpha_2 S_-^2 \cdot C_-^1 + \gamma_2 \alpha_1 C_+^2 \cdot S_+^1 + \gamma_1 \alpha_2 S_+^2 \cdot C_+^1 + \gamma_1 \alpha_1 C_-^2 \cdot S_-^1)(\omega), \\ D_{22}(\omega) &= (\gamma_2 \alpha_2 S_-^2 \cdot S_-^1 + \gamma_2 \alpha_1 C_+^2 \cdot C_-^1 + \gamma_1 \alpha_2 S_+^2 \cdot S_+^1 + \gamma_1 \alpha_1 C_-^2 \cdot C_+^1)(\omega). \end{aligned}$$

We put

$$\begin{aligned} d(\omega) &:= 4 \det D(\omega) \\ &= 4\gamma_2^2 \alpha_2 \alpha_1 (S_+^2 \cdot S_-^2 - C_+^2 \cdot C_-^2) \cdot (S_+^1 \cdot S_-^1 - C_-^1 \cdot C_+^1)(\omega) \\ &\quad + 4\gamma_2 \gamma_1 \alpha_2^2 (S_+^2 \cdot C_+^2 - S_-^2 \cdot C_-^2) \cdot (S_+^1 \cdot C_-^1 - C_+^1 \cdot S_-^1)(\omega) \\ &\quad + 8\gamma_2 \gamma_1 \alpha_2 \alpha_1 (S_+^2 \cdot S_+^2 - C_+^2 \cdot C_-^2) \cdot (S_+^1 \cdot S_+^1 - C_+^1 \cdot C_-^1)(\omega) \\ &\quad + 4\gamma_2 \gamma_1 \alpha_1^2 (S_+^2 \cdot C_-^2 - C_+^2 \cdot S_-^2) \cdot (S_+^1 \cdot C_+^1 - S_-^1 \cdot C_-^1)(\omega) \\ &\quad + 4\gamma_1^2 \alpha_1 \alpha_2 (S_+^2 \cdot S_-^2 - C_-^2 \cdot C_+^2) \cdot (S_+^1 \cdot S_-^1 - C_+^1 \cdot C_+^1)(\omega). \end{aligned} \quad (6)$$

By (4), (5), we have

$$D(\omega) \begin{pmatrix} p_3^1 \\ p_4^1 \end{pmatrix} = 0.$$

Since  $\phi$  is an eigenfunction if and only if  $(p_3^1, p_4^1) \neq 0$ , we see that  $\lambda = \omega^4$  is an eigenvalue of  $\mathcal{A}$  if  $d(\omega) = 0$ ,  $\omega > 0$ . Let  $\omega_n$ ,  $n \in \mathbb{N}$ , is the  $n$ -th positive zero of  $d(\omega)$ . Then  $\lambda_n := \omega_n^4$ ,

$0 < \omega_1 < \omega_2 < \dots$ , is the  $n$ -th eigenvalue of  $\mathcal{A}$ . We can verify that  $\lambda_n$  is a simple eigenvalue. Let  $\phi^n$  be an eigenfunction corresponding to  $\lambda_n$ , normalized in  $H$ . In the following, let  $\varphi(\omega)$  be a function defined by

$$\varphi(\omega) = A \cos \beta_1 \omega \cos \beta_2 \omega - B \sin \beta_1 \omega \sin \beta_2 \omega + C \sin(\beta_1 - \beta_2) \omega \quad (7)$$

where  $A = (\gamma_1 \alpha_1 + \gamma_2 \alpha_2)(\gamma_1 \alpha_2 + \gamma_2 \alpha_1)$ ,  $B = \gamma_1 \gamma_2 (\alpha_1 + \alpha_2)^2$ ,  $C = \gamma_1 \gamma_2 (\alpha_1^2 - \alpha_2^2)$ . We denote the  $n$ -th positive zero of  $\varphi$  by  $\mu_n$ .

**Lemma 2**  $d(\omega)$  is written as

$$d(\omega) = e^{(\beta_1 + \beta_2)\omega} (\varphi(\omega) - h(\omega)), \quad \omega \in \mathbf{R}$$

where  $h(\omega) \in C^1(\mathbf{R})$  and  $h(\omega) \rightarrow 0$ ,  $h'(\omega) \rightarrow 0$  exponentially as  $\omega \rightarrow \infty$ .

**Proof** By (6),  $h(\omega) = \varphi(\omega) - e^{-(\beta_1 + \beta_2)\omega} d(\omega)$  and  $h'(\omega)$  converge to 0 exponentially as  $\omega \rightarrow \infty$ .

To discuss controllability, we treat the moment problem on the system (1)(2)(3)(4). According to Krabs [4] or Russell [12], to solve the moment problem, we need the following conditions:

$$\liminf_{n \rightarrow \infty} (\omega_{n+1}^2 - \omega_n^2) > \frac{2\pi}{T}, \quad (8)$$

$$\limsup_{y \rightarrow \infty} \limsup_{x \rightarrow \infty} \frac{d(x+y) - d(x)}{y} < \frac{T}{2\pi} \quad (9)$$

where  $d(x)$  = number of  $\omega_j$  with  $\omega_j < x^2$ . The aim of this paper is to prove the following

**Theorem 1** We have

- (1) There exist  $M$  and  $N$  such that  $\omega_{M+n} - \mu_{N+n} \rightarrow 0$ ,
- (2)  $0 < \frac{1}{a}(\pi - \sin^{-1} k) \leq \liminf_{n \rightarrow \infty} (\omega_{n+1} - \omega_n) \leq \limsup_{n \rightarrow \infty} (\omega_{n+1} - \omega_n) < \infty$ ,
- (3)  $\lim_{n \rightarrow \infty} (\omega_{n+1}^2 - \omega_n^2) = \infty$ .

By this theorem, it is clear that  $\{\omega_n\}_{n \in \mathbf{N}}$  satisfies the condition (8). Moreover, the condition (8) verify the condition (9).

Some simple facts for  $\varphi(\omega)$  are given in the following

**Lemma 3** In the formula (7), we have

- (1)  $A \geq B > 0$ ,
- (2)  $A = B$  if and only if  $\rho_1 T_1 = \rho_2 T_2$ .
- (3)  $C = 0$  if and only if  $\rho_1 T_2 = \rho_2 T_1$ .
- (4)  $A = B$ ,  $C = 0$  if and only if  $(\rho_1, T_1) = (\rho_2, T_2)$ .
- (5)  $A > B$  or  $C \neq 0$  if and only if  $(\rho_1, T_1) \neq (\rho_2, T_2)$ .

(6)  $\varphi$  is written as

$$\varphi(\omega) = D(\cos a\omega + k \sin(b\omega + \tau)), \quad 0 \leq k < 1 \quad (10)$$

where  $D = (A+B)/2$ ,  $a = \beta_1 + \beta_2$ ,  $b = \beta_1 - \beta_2$ ,  $k = R/D$ ,  $R = \sqrt{((A-B)/2)^2 + C^2}$ ,  $\tau = \cos^{-1}(C/R) \in [0, \pi]$  for  $R \neq 0$  and  $\tau = 0$  for  $R = 0$ .

**Proof** We see (1) from  $A = B + \alpha_1\alpha_2(\gamma_1 - \gamma_2)^2 \geq B > 0$ . The assertions (2), (3), (4) and (5) are clear. We have (6) since

$$\begin{aligned} \varphi(\omega) &= \frac{A+B}{2} \cos(\beta_1 + \beta_2)\omega + \frac{A-B}{2} \cos(\beta_1 - \beta_2)\omega + C \sin(\beta_1 - \beta_2)\omega \\ &= D \cos a\omega + R \sin(b\omega + \tau) = D(\cos a\omega + k \sin(b\omega + \tau)). \end{aligned}$$

where  $k \geq 0$  satisfies

$$k^2 = \frac{R^2}{D^2} = \frac{(A+B)^2 - 4(AB - C^2)}{(A+B)^2} = 1 - \frac{4(\gamma_1 + \gamma_2)^2 \gamma_1 \gamma_2 (\alpha_1 + \alpha_2)^2 \alpha_1 \alpha_2}{(A+B)^2} < 1.$$

We assume  $\beta_1 \geq \beta_2 > 0$  for simplicity. So we have  $a > b \geq 0$ . We put  $f_k(\omega) = \cos a\omega + k \sin(b\omega + \tau)$ . Since  $f_k(\omega) = 0$  implies  $|\cos a\omega| = |k \sin(b\omega + \tau)| \leq k$ , all the positive zeros of  $\varphi(\omega)$  are in the set  $\{\omega > 0; |\cos a\omega| \leq k\} = \bigcup_{n=1}^{\infty} \mathcal{I}_n(k)$ ,  $\mathcal{I}_n(k) = [s_n(k), t_n(k)] \subset \mathcal{J}_n = [(n-1)\pi/a, n\pi/a]$ ,  $n = 1, 2, \dots$  where  $s_n(k) = (2n-1)\pi/2a - \sin^{-1} k/a$ ,  $t_n(k) = (2n-1)\pi/2a + \sin^{-1} k/a$ . We write  $\mathcal{I}_n = \mathcal{I}_n(k)$ ,  $s_n = s_n(k)$ ,  $t_n = t_n(k)$  and  $f(\omega) = f_k(\omega)$ . In Theorem 2 below, we prove that there exists exactly one zero of  $f$  in each  $\mathcal{I}_n \subset \mathcal{J}_n$ .

**Theorem 2** For each  $n \in \mathbb{N}$ , there exist  $u_n, v_n \in \mathcal{I}_n$  such that

- (1)  $f(u_n) = 1 - k = -f(v_n)$  and  $f(\omega)$  is monotone decreasing on  $[u_n, v_n]$  for odd  $n$ ,
- (2)  $f(u_n) = k - 1 = -f(v_n)$  and  $f(\omega)$  is monotone increasing on  $[u_n, v_n]$  for even  $n$ ,
- (3)  $|f(\omega)| \geq 1 - k$  for  $\omega \in \mathcal{J}_n \setminus [u_n, v_n]$
- (4) only zero of  $f$  exists in  $(u_n, v_n)$  for any  $n$ , which implies that  $\mu_n \in \mathcal{I}_n$  for any  $n \in \mathbb{N}$ .

First, we show, for sufficiently small  $k$ ,  $\mu_n \in \mathcal{I}_n$  for every  $n \in \mathbb{N}$ .

**Lemma 4** Let  $k \in [0, 1/\sqrt{2}]$ . Then we have

- (1) for odd  $n$ ,  $f(s_n) \geq 0 \geq f(t_n)$  and  $f(\omega)$  is monotone decreasing on  $[s_n, t_n]$ ,
  - (2) for even  $n$ ,  $f(t_n) \geq 0 \geq f(s_n)$  and  $f(\omega)$  is monotone increasing on  $[s_n, t_n]$ ,
- Consequently, in  $\mathcal{J}_n$ ,  $f(\omega)$  has only one zero in  $[s_n, t_n]$ .

**Proof** We only show (1). (2) is proved similarly.

$$\begin{aligned} f(s_n) &= \cos\left(\frac{(2n-1)\pi}{2} - \sin^{-1} k\right) - k \sin(bs_n + \tau) \\ &= (-1)^{n+1}k - k \sin(bs_n + \tau) = k - k \sin(bs_n + \tau) \geq 0 \\ f(t_n) &= (-1)^n k - k \sin(bs_n + \tau) = -k - k \sin(bs_n + \tau) \leq -k + k = 0. \end{aligned}$$

In  $[s_n, t_n]$ , we have  $\sin a\omega \geq 1/\sqrt{2}$  and

$$f'(\omega) = -a \sin a\omega + kb \cos(b\omega + \tau) \leq -a/\sqrt{2} + b/\sqrt{2} < 0.$$

In the following, we put  $\bar{k} = kb^2/a^2$ ,  $\bar{s}_n = s_n(\bar{k})$ ,  $\bar{t}_n = t_n(\bar{k})$ ,  $\bar{\mathcal{I}}_n = \mathcal{I}_n(\bar{k})$ , and  $\bar{\mu}_n = \mu_n(\bar{k})$ ,  $\bar{f}(\omega) = f_{\bar{k}}(\omega)$  and  $S = \{k \in [0, 1); \mu_n(k) \in \mathcal{I}_n(k) \subset \mathcal{J}_n \text{ for each } n \in \mathbb{N}\}$ .

**Lemma 5** *For  $\bar{k} \in S$ , the conclusion of Theorem 2 is valid.*

**Proof** We have

$$\begin{aligned} f''(\omega) &= f''_k(\omega) = -a^2 \cos a\omega - kb^2 \sin(b\omega + \tau) \\ &= -a^2(\cos a\omega + \bar{k} \sin(b\omega + \tau)) = -a^2 \bar{f}_k(\omega) = -a^2 \bar{f}(\omega). \end{aligned}$$

Let  $n$  be odd. The case where  $n$  is even is also treated similarly. Then  $\bar{f}((n-1)\pi/a) \geq 1 - k > 0 > k - 1 \geq \bar{f}(\pi/a)$ . Since  $\bar{\mu}_n$  is the only zero of  $\bar{f}$  in  $((n-1)\pi/a, n\pi/a)$ , we have  $f''(\omega) < 0$  for  $\omega \in ((n-1)\pi/a, \bar{\mu}_n)$ ,  $f''(\omega) > 0$  for  $\omega \in (\bar{\mu}_n, n\pi/a)$ . Thus  $f(\omega)$  is concave on  $((n-1)\pi/a, \mu_n)$  and convex on  $(\mu_n, n\pi/a)$ . Let  $y_n, z_n \in \mathcal{J}_n$  with  $f(y_n) = \max_{\omega \in \mathcal{I}_n} f(\omega) \geq 1 - k$  and  $f(z_n) = \min_{\omega \in \mathcal{I}_n} f(\omega) \leq k - 1$ . Then, we find  $u_n, v_n$  with  $s_n \leq y_n < \mu_n < v_n \leq z_n \leq t_n$  such that  $f(u_n) = 1 - k$  and  $f(v_n) = k - 1$ . Thus,  $f$  is monotone decreasing on  $[u_n, v_n] \subset [y_n, z_n]$ .

**Proof of Theorem 2** There exists  $N \in \mathbb{N}$  such that  $0 \leq (b/a)^{2N} \leq 1/2$ . Let  $k \in [0, 1)$  and  $k_i = k(b/a)^{2i}$ ,  $i = 0, 1, 2, \dots, N$ . Then  $k_N \in S$  by Lemma 4. Therefore, by Lemma 5,  $k_i \in S$ ,  $i = 1, 2, \dots, N - 1$ . In particular,  $k_1 = k(b/a)^2 = \bar{k} \in S$ . Thus, by using Lemma 5 again, we can prove Theorem 2.

Next, we want to show that, for sufficiently large  $n$ , there exists only one zero of  $d(\omega)$  in each  $\mathcal{J}_n$ . More precisely, we have

**Theorem 3** *There exists  $M, N \in \mathbb{N}$  such that  $\omega_{M+n} \in \mathcal{J}_{N+n}$  for  $n = 0, 1, \dots$ .*

To prove the above theorem, we prepare Lemma 6 and lemma 7 given below:

**Lemma 6** *For any  $n \in \mathbb{N}$ , the following inequality holds:*

$$|f'(\mu_n)| \geq \delta = \sqrt{(1 - k^2)(a^2 - b^2)}. \quad (11)$$

**Proof** Since  $\mu_n, n \in \mathbb{N}$ , are zeros of  $f$ , we have

$$f(\mu_n) = \cos a\mu_n + k \sin(b\mu_n + \tau) = 0, \quad (12)$$

$$f'(\mu_n) = -a \sin a\mu_n + kb \cos(b\mu_n + \tau). \quad (13)$$

If  $b = 0$ , then  $(f'(\mu_n))^2 = a^2 \sin^2 a\mu_n = a^2(1 - \cos^2 \tau) \geq a^2(1 - k^2)$ . Hence we have (11). If  $b \neq 0$ , then

$$\begin{aligned} f'(\mu_n)^2 &= \frac{(a^2 - b^2)}{b^2} \left( \sin a\mu_n - \frac{af'(\mu_n)}{a^2 - b^2} \right)^2 + (1 - k^2)(a^2 - b^2) \\ &\geq (1 - k^2)(a^2 - b^2). \end{aligned}$$

Thus we have (11).

**Lemma 7** *There exists an interval  $[a_n, b_n] \subset [u_n, v_n]$  and  $l \in [0, 1 - k]$  such that*

$$|f(\omega)| \leq l, \quad |f'(\omega)| \geq \delta/2 \quad \text{for } \omega \in [a_n, b_n], \quad (14)$$

$$|f(\omega)| \geq l \quad \text{for } \omega \in \mathcal{J}_n \setminus [a_n, b_n]. \quad (15)$$

**Proof** By uniform continuity of  $f'(\omega)$  and Lemma 6, there exists  $c > 0$  with  $l = \delta c/2 < 1 - k$  such that

$$|f'(\omega)| \geq \delta/2 \quad \text{for } \omega \in [\mu_n - c, \mu_n + c]. \quad (16)$$

Therefore, we have  $|f(\omega)| \geq (\delta/2)|\omega - \mu_n|$  on  $[\mu_n - c, \mu_n + c]$ . If  $n$  is odd (resp. even), we define  $a_n, b_n$  with  $\mu_n - c < a_n < b_n < \mu_n + c$  by  $f(a_n) = l$  (resp.  $-l$ ) and  $f(b_n) = -l$  (resp.  $l$ ). Hence we have

$$\{\omega \in [\mu_n - c, \mu_n + c]; |f(\omega)| \leq l\} = [a_n, b_n]. \quad (17)$$

By (16) and (17), we see (14), and by Theorem 3, (15).

We put  $g(\omega) = \varphi(\omega) - h(\omega) = Df(\omega) - h(\omega)$ . Since  $h(\omega), h'(\omega) \rightarrow 0$  as  $\omega \rightarrow \infty$ , there exists  $N \in \mathbb{N}$  such that  $|h(\omega)| < Dl$  and  $|h'(\omega)| < D\delta/2$  for  $\omega > (N - 1)\pi/a$ .

Let  $n$  be odd with  $n > N$ . Then, by Lemma 7, we have  $f(a_n) = l, f(b_n) = -l$  and  $f'(\omega) < -\delta/2$  for  $\omega \in [a_n, b_n]$ . Hence  $g(a_n) = Df(a_n) - h(a_n) = Dl - h(a_n) > Dl - Dl = 0$  and  $g(b_n) = Df(b_n) - h(b_n) = Dl - h(b_n) < -Dl + Dl = 0$ . Thus, for  $\omega \in [a_n, b_n]$ ,  $g'(\omega) = Df'(\omega) - h'(\omega) \leq -D\delta/2 + |h'(\omega)| < -D\delta/2 + D\delta/2 = 0$  which implies that  $g(\omega)$  has a unique zero in  $(a_n, b_n)$ . For  $\omega \in \mathcal{J}_n \setminus [a_n, b_n]$ , by (14), we have  $|g(\omega)| \geq |Df(\omega)| - |h(\omega)| \geq Dl - Dl = 0$ . Therefore,  $g(\omega)$  has a unique zero in  $\mathcal{J}_n$ . The case with even  $n \geq N$  is also similarly proved. Let  $\omega_M$  be a zero of  $g(\omega)$  in  $\mathcal{J}_N$ . Thus  $\omega_{M+n} \in \mathcal{J}_{N+n}$  for  $n = 0, 1, 2, \dots$

**Proof of Theorem 1** Since  $f(\mu_{N+n}) = g(\omega_{M+n}) = 0$ , we have

$$h(\omega_{M+n}) = Df(\omega_{M+n}) - g(\omega_{M+n}) = D(f(\omega_{M+n}) - f(\mu_{N+n})). \quad (18)$$

By Mean Value Theorem, there exists  $\theta \in (0, 1)$  such that  $f(\omega_{M+n}) - f(\mu_{N+n}) = (\omega_{M+n} - \mu_{N+n})f'(\mu_{N+n} + \theta(\omega_{M+n} - \mu_{N+n}))$ . Thus, by (14) and (18),

$$|\omega_{M+n} - \mu_{N+n}| \leq \frac{|f(\omega_{M+n}) - f(\mu_{N+n})|}{|f'(\mu_{N+n} + \theta(\omega_{M+n} - \mu_{N+n}))|} \leq \frac{2}{D\delta} |h(\omega_{M+n})| \rightarrow 0$$

as  $n \rightarrow \infty$ . Therefore,

$$\begin{aligned} \liminf_{n \rightarrow \infty} (\omega_{n+1} - \omega_n) &= \liminf_{n \rightarrow \infty} (\omega_{M+n+1} - \omega_{M+n}) \\ &= \liminf_{n \rightarrow \infty} (\omega_{M+n+1} - \mu_{N+n+1} + \mu_{N+n+1} - \mu_{N+n} + \mu_{N+n} - \omega_{M+n}) \\ &= \liminf_{n \rightarrow \infty} (\mu_{N+n+1} - \mu_{N+n}) = \liminf_{n \rightarrow \infty} (\mu_{n+1} - \mu_n). \end{aligned}$$

By  $s_n < \mu_n < t_n < s_{n+1} < \mu_{n+1} < t_{n+1}$ , we have

$$\begin{aligned} \mu_{n+1} - \mu_n &\geq s_{n+1} - t_n = \left( \frac{2n+1}{2a} \pi - \frac{\sin^{-1} k}{a} \right) - \left( \frac{2n-1}{2a} \pi + \frac{\sin^{-1} k}{a} \right) \\ &= \frac{\pi}{a} - \frac{2 \sin^{-1} k}{a} = \frac{1}{a} (\pi - 2 \sin^{-1} k) \end{aligned}$$

The above theorem implies that

$$\liminf_{n \rightarrow \infty} (\omega_{n+1}^2 - \omega_n^2) \geq \liminf_{n \rightarrow \infty} (\omega_{n+1} + \omega_n) \liminf_{n \rightarrow \infty} (\omega_{n+1} - \omega_n) = \infty. \quad (19)$$



### 3 Concluding Remarks

This paper is only a first step to the controllability theory for the Euler-Bernoulli equation using the moment problem method [4], [12].

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